The BE1-32R Directional Overpower Relay and the BE1-32 O/U Directional Over/Underpower Relay are solid-state devices which provide versatility and control in protecting machines against reverse power flow, underpower and overpower conditions.

ADVANTAGES

- Measures Real Power - $E \cos \Theta$.
- Wide variety of input configurations are available including single-phase and three phase, 3 and 4 wire systems.
- Sensing ranges available from 0.5 to 6000 watts secondary.
- Instantaneous, definite and inverse timing characteristics available.
- Low input sensing and supply burdens.
- Qualified to the requirements of IEEE C37.90.1-1989 and IEC 255 for fast transient and surge withstand capability; IEC 255-5 for impulse.
- UL recognized under Standard 508, UL File #E97033.
- Five year warranty.

ADDITIONAL INFORMATION

INSTRUCTION MANUAL
Request Publication 9171100990

STANDARDS, DIMENSIONS, AND ACCESSORIES
Request bulletin SDA
APPLICATION

PURPOSE

The BE1-32R Directional Overpower Relay and the BE1-32 O/U, Directional Over/Underpower Relays sense real power flow (E_l cos Θ). These relays are solid-state devices designed for use in single-phase or three-phase systems to provide equipment protection for overpower and/or underpower or to be used for supervisory control of circuits. Both relay configurations may be used to monitor either forward or reverse power. In the following application examples, single-phase connections are shown for simplicity.

APPLICATION EXAMPLES

The BE1-32 relays (R and O/U) are typically used in applications where excessive power flow in the tripping direction is indicative of undesirable situations. Typical examples are discussed below:

EXAMPLE 1 - ANTI MOTORING

In this example, the power relay is used to protect the prime mover rather than the generator. When an ac generator, operating in parallel with a power system, loses prime mover torque, it remains in synchronism with the system and continues to run as a synchronous motor drawing sufficient power from the system to drive the prime mover. Sustained motoring can cause severe damage to the prime mover. The Directional Power Relay, with its wide sensitivity range, can detect levels of reverse real power flow as low as 0.5 Watts secondary and provide an alarm or trip the unit off line (See Figure 1). In this example, single phase sensing is usually considered sufficient, since motoring is a balanced condition.

EXAMPLE 2 - COGENERATOR CONTROL

Given that a co-generation system has automatic engine controls, auto synchronizer, and automatic kW and kVar controls, the system will virtually operate by itself. The only functions not readily apparent are the start/stop signals to the generators. Two system configurations using a Power Relay may be utilized to generate contact closures for start and/or stop signals.

The first configuration (Figure 2) shows a power relay connected to the utility to sense kW. The pickup point of the relay is set at the maximum desired utility power level. If the power relay contact closes, the generator will be started and automatically paralleled with the utility system. A time delay of 15 seconds or more is generally included in the “start” circuit to ignore transient overload conditions.

Figure 1 - Power Relay Motoring Protection

Figure 2 - Power Relay Start Control
APPLICATION, continued

When the generator is paralleled and loaded, the kW signal will decrease by the amount of load the generator accepted. An underpower relay can measure utility power and generate a “stop” signal when utility power decreased below a selected level. A definite time delay will generally be provided for the “stop” signal of one minute or more. The Basler Model BE1-32 O/U Power Relay incorporates both over and under power sensing in one relay, which makes it ideal for this application.

In the second configuration (Figure 3) the “start” signal is generated as in that of Figure 2. The setpoint of the start signal should be above the import power setting. The “stop” signal will require an underpower relay on the generator output. This system is illustrated in Figure 3.

EXAMPLE 3 - GENERATOR OVERLOAD

Refer to Figure 3. Whenever excessive load has been connected to a generating system, the Power Relay will initiate the corrective action by energizing an alarm to alert the station operator or will initiate an automatic sequence to either shed non-critical load or start and parallel an in-house generator to assume the excess load.

EXAMPLE 4 - DISTRIBUTION SYSTEM OVERLOAD

Another typical use, addressing excessive load, concerns distribution protection, see Figure 4. A high-voltage bus supplies two transformers. T1 and T2 together can supply all connected load. However, neither T1 or T2 is capable of supplying the total load. To provide adequate protection for the distribution system, the overpower function is used to sense overload conditions on each transformer and the underpower function is used to sense power flowing through the transformers in an undesired direction.

EXAMPLE 5 - REACTIVE POWER (VARs) DETECTION

This example deals with the Directional Power Relay’s ability to measure real or reactive power.

Real power (watts) is supplied to the generator by the prime mover, and reactive power (vars) is supplied to the field by the exciter. When field excitation is significantly reduced and the connected system can provide sufficient reactive power to maintain the generator’s terminal voltage, reactive power will flow into the machine and cause it to operate as an induction generator with essentially the same kW output. This situation causes problems; first, the additional reactive loading of the faulty generator must be redistributed to other synchronous generators on the system. Secondly, a synchronous generator is not designed to function as an induction generator. Excessive heating occurs in the damper (Amortisseur) windings, slot wedges, and in the surface iron of the rotor due to slip frequency current flow which results when a synchronous generator is operated as an induction generator. The Directional Power Relay can be applied to respond to this reactive power flow.

The Basler BE1-32 Directional Power Relay is designed to respond to true power as defined by the equation:

\[ P = El \cos \Theta \]

where:
- \( P \) = real power (watts)
- \( E \) = effective emf or system voltage
- \( I \) = effective current
- \( \Theta \) = the phase angle between \( E \) and \( I \)
However, reactive power is defined by the equation:

\[ Q = EI \sin \theta \]

Since the sine of \( Q \) equals the cosine of \( (Q - 90°) \), the relay can be connected to measure only reactive power by adding \( 90° \) in the connection of the PTs as shown in Figure 5. The relay is now capable of detecting the inability of the excitation system to supply adequate reactive power.

With the many options and combinations of options available, the Basler Electric Directional Power Relays can be adapted to multitude of systems and situations to provide the utmost in overpower and underpower protection of system equipment.

**SPECIFICATIONS**

**FUNCTIONAL DESCRIPTION**

The specifications on these pages define the many features and options that can be combined to exactly satisfy a specific application requirement. The block diagram, Figure 6, illustrates how the various standard features, as well as the options, function together.

**INPUTS**

**Current Sensing**

System current transformers (CTs) with nominal 5 A secondaries supply the Directional Power Relay's input transformers with one, two or three phase currents. If sensing input range 1, 4 or 7 is selected, the input transformers are capable of 7 A continuous current, 10 A for 1 minute and 140 A for 1 second.
If sensing input range 2, 3, 5, 6, 8 or 9 is selected, the input transformers are capable of 10 A continuous current, 15 A for 1 minute and 200 A for 1 second.

Maximum burden for each current input (2 terminals) is 1 VA at threshold over the frequency range of 45 to 65 Hz.

**Voltage Sensing**

System potential transformers (PTs) with 120 or 240V secondaries supply the Directional Power Relay's input transformers with single or three-phase voltages. The voltage sensing inputs are nominally rated at 100 or 220V (50 Hz) and 120 or 240V (60 Hz) with a maximum burden of 1 VA per input (2 terminals) over the frequency range of 45 to 65 Hz. Maximum continuous voltage is limited to 150% nominal.

**SENSING INPUT TYPES**

There are 6 sensing input types as defined by the Style Chart (page 12). The Directional Power Relay's input circuitry receives voltage and current signals from system PTs and CTs. The CT signal is adjusted in level by a front panel range switch before it is applied to the kW transducer circuitry. Several input circuit configurations are available, the selection of which is determined by the specific application. The following paragraphs provide a brief description of each input sensing type and their calibration

**Type A Sensing:** Single-Phase (Figure 7). The type A sensing configuration monitors line-to-neutral voltage and a single phase current of a three-phase, four-wire circuit and calculates the power flowing in the tripping direction. Relays with this sensing type are calibrated in single-phase watts.

**Type B (60 Hz) or Type V (50 Hz) Sensing:** Single-Phase (Figure 8) with 30° phase shift. This sensing configuration monitors a line-to-line voltage and a single phase current of a three-phase, three-wire circuit and calculates the power flowing in the tripping direction. Since the input voltage leads the input current by 30° (assuming unity power factor) a 30° lagging phase shift network is designed into the voltage input circuit. Relays with this sensing type are calibrated in single-phase watts. Note: Type B or V configurations are phase rotation sensitive.

**Type C Sensing:** Three-phase Scott Tee (Figure 9). The type C sensing configuration monitors three line-to-line voltages and a single phase current of a three-phase, three-wire circuit and calculates the power flowing in the tripping direction. The relay measures actual power even if the system voltages are not balanced. Relays with this sensing type are calibrated in three-phase watts.

**TRIPPING DIRECTION**

\[
P = E (B-N) I_B \cos \theta
\]

**Figure 7 - Single Phase, Type A Sensing**

**Figure 8 - Single Phase, Type B or V Sensing**

**Figure 9 - Three Phase, Type C Sensing**
**Type D Sensing:** Three-Phase (Figure 10). The type D sensing configuration monitors three line-to-neutral voltages and three phase currents of a three-phase, four-wire circuit and calculates the power flowing in the tripping direction. Relays with this sensing type are calibrated in three-phase watts.

**Figure 10 - Three Phase, Type D Sensing**

**Type E Sensing:** Three-Phase (Figure 11). The type E sensing configuration monitors three line-to-line voltages and two of the phase currents of a three-phase, three-wire circuit and calculates the power flowing in the tripping direction. The power equation assumes that conditions are balanced. Relays with this sensing type are calibrated in three-phase watts. Note: Type E configurations are phase rotation sensitive.

**Figure 11 - Three Phase, Type E Sensing**

**Power Supply**

One of five power supply boxes may be selected to provide internal operating power. They are described in Table 1.

**Table 1 - Power Supply Options**

<table>
<thead>
<tr>
<th>Type</th>
<th>Nominal Input Voltage</th>
<th>Input Voltage Range</th>
<th>Burden at Nominal</th>
</tr>
</thead>
<tbody>
<tr>
<td>O</td>
<td>48 Vdc</td>
<td>24 to 150 Vdc</td>
<td>5.0 W</td>
</tr>
<tr>
<td>P</td>
<td>125 Vdc/120 Vac</td>
<td>24 to 150 Vdc/90 to 132 Vac</td>
<td>5.2 W/15.1 VA</td>
</tr>
<tr>
<td>tR</td>
<td>24 Vdc</td>
<td>12 to 32 Vdc</td>
<td>5.1 W</td>
</tr>
<tr>
<td>T</td>
<td>250 Vdc/240 Vac</td>
<td>62 to 280 Vdc/90 to 270 Vac</td>
<td>5.2 W/14.0 VA</td>
</tr>
</tbody>
</table>

† Type R Power Supply may require 14 Vdc to begin operation. Once operating, the voltage may be reduced to 12 Vdc.

**POWER RANGE PICKUP**

Overpower pickup of the relay is adjustable by means of a front panel 10 position rotary TAP select switch used in conjunction with the front panel HIGH/LOW switch over the defined ranges listed in Table 2. Underpower pickup is continuously adjustable from 10 to 95% of the selected overpower tap. Pickup accuracy is ±2% (or ±0.05 watts one phase; ±0.15 watts 3 phase) of the front panel setting for unity power factor. Pickup accuracy is ±5% of the front panel setting for all other power factors (0.5<pf<1.0). The range of voltage for proper operation is 40 to 150 percent of the nominal value.

When the calculated value for power exceeds the overpower pickup setting or falls below the underpower pickup setting and is in the tripping direction, the appropriate LED is illuminated and timing is initiated. One indicating LED is provided for each measuring function within the relay.

**KW TRANSDUCER**

The kW Transducer samples the current and voltage of each phase on a continuous basis. The resulting signals representing current and voltage are multiplied and integrated to develop a dc voltage level that is representative of true kW.

**COMPARATOR CIRCUITS**

The dc output of the kW Transducer is then compared to front panel settings for underpower and/or overpower. When the reference level of the comparator (or comparators if applicable) is crossed, the output of the comparator is used to either energize the appropriate output (if instantaneous timing has been specified) or to initiate the timing circuits (definite, or inverse).

**TIMING**

Time delay is defined as the elapsed time between the application of the condition to the input terminals of the relay and the transition of the output contacts.
SPECIFICATIONS, continued

<table>
<thead>
<tr>
<th>Sensing Input Type</th>
<th>Nominal Volts</th>
<th>Range</th>
<th>Switch Positions (in Watts)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>A</td>
</tr>
<tr>
<td>A, B, or V 1</td>
<td>120</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>HI</td>
<td>2.0</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>Lo</td>
<td>0.5</td>
</tr>
<tr>
<td>2</td>
<td>10</td>
<td>HI</td>
<td>20</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>Lo</td>
<td>5</td>
</tr>
<tr>
<td>3</td>
<td>100</td>
<td>HI</td>
<td>25</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>Lo</td>
<td>25</td>
</tr>
<tr>
<td>C, D, or E 1</td>
<td>120</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>6</td>
<td>HI</td>
<td>6.0</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>Lo</td>
<td>1.5</td>
</tr>
<tr>
<td>2</td>
<td>60</td>
<td>HI</td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>Lo</td>
<td>15</td>
</tr>
<tr>
<td>3</td>
<td>300</td>
<td>HI</td>
<td>300</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>Lo</td>
<td>75</td>
</tr>
<tr>
<td>A, B, or V 208 or 240</td>
<td>5, 8</td>
<td>HI</td>
<td>4.0</td>
</tr>
<tr>
<td></td>
<td>5</td>
<td>Lo</td>
<td>1.0</td>
</tr>
<tr>
<td>4</td>
<td>80</td>
<td>HI</td>
<td>80</td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>Lo</td>
<td>10</td>
</tr>
<tr>
<td>5</td>
<td>200</td>
<td>HI</td>
<td>200</td>
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<td></td>
<td>5</td>
<td>Lo</td>
<td>50</td>
</tr>
<tr>
<td>6</td>
<td>600</td>
<td>HI</td>
<td>600</td>
</tr>
<tr>
<td></td>
<td>6</td>
<td>Lo</td>
<td>150</td>
</tr>
</tbody>
</table>

Table 2 - Power Range Pickup Settings

Each model, BE1-32R or BE1-32O/U is capable of instantaneous trip, definite time delay trip, or an inverse time delayed trip as defined and selected by the Style Chart.

Instantaneous response time of the relay is within 80 ms (60 Hz) or 100 ms (50 Hz) for a real power magnitude of 2 times the setting.

The definite time delay is adjustable over the ranges of 0.1 to 9.9 seconds and 01 to 99 seconds. Selection of the ranges is accomplished by a front-panel multiplier switch which selects either 0.1 or 1.0 as a multiplier of the front panel Time Dial thumbwheel switch. (A Time Dial setting of 00 enables instantaneous operation.) Definite timing accuracy is ±5% of the setting or 50 ms, whichever is greater.

Inverse time delayed trip is available for the overpower function only. The inverse time delay curve is adjustable from 01 to 99 by means of a front-panel thumbwheel switch. Incrementing the thumbwheel switch moves the inverse curve along the vertical axis. (See Figure 12 for Inverse Time Characteristics.) A Time Dial setting of 00 enables instantaneous operation. Inverse time is accurate to within ±5% of the published curve or 50 ms, whichever is greater.

POWER SUPPLY STATUS OUTPUT (OPTIONAL)

The power supply status output relay is energized and its NC output contact is opened when power is applied to the relay. Normal internal relay operating voltage maintains the power supply status output relay continuously energized with its output contact open. If the power supply output voltage falls below the requirements of proper operation, the power supply output relay is deenergized, closing the NC output contact.
TARGETS
Magnetically latched, manually reset target indicators are optionally available to indicate that a trip output has energized. Either internally operated or current operated target may be specified. Current operated targets require 0.2 A in the output trip circuit to actuate, and trip current must not exceed 30 A for 0.2 seconds, 7 A for 2 minutes, and 3 A continuous. Current operated targets may be selected only when normally open (NO) output contacts have been specified.

PUSH-TO-ENERGIZE-OUTPUT PUSHBUTTONS
Applying a thin non-conducting rod through a hole in the front panel energizes each output relay for testing the external trip circuits.

SURGE WITHSTAND CAPABILITY
Qualified to IEEE C37.90.1-1989 Surge Withstand Capability Test and IEC 255.

FAST TRANSIENT
Qualified to IEEE C37.90.1-1989 Fast Transient Test.

IMPULSE TEST
Qualified to IEC 255-5.

MECHANICAL

Operating Temperature
-40°C(-40°F) to +70°C(+158°F).

Storage Temperature
-65°C(-85°F) to +100°C(+212°F).

Weight
M1 - 18.5 pounds max.
S1 - 13.5 pounds max.

Shock
In standard tests, the relay has withstood 15g in each of three mutually perpendicular axes without structural damage or degradation of performance.

Vibration
In standard tests, the relay has withstood 2g in each of three mutually perpendicular axes swept over the range of 10 to 500 Hz for a total of six sweeps, 15 minutes each sweep, without structural damage or degradation of performance.

OUTPUTS
Output contacts are rated as follows:

Resistive
120/240 Vac - make 30 A for 0.2 seconds, carry 7 A continuously, break 7 A.

250 Vdc - make and carry 30 A for 0.2 seconds, carry 7 A continuously, break 0.3 A.

500 Vdc - make and carry 15 A for 0.2 seconds, carry 7 A continuously, break 0.1 A.

Inductive
120/240 Vac, 125 Vdc, 250 Vdc - break 0.3 A (L/R = 0.04).

Figure 12 - Overpower Inverse Characteristics
Figure 13 - Sensing Connections
(Continued next page)
CONNECTIONS
(continued)

Figure 13 (continued) - Sensing Connections

Figure 14 - Control Circuits
**ORDERING**

**MODEL NUMBER**


**STYLE NUMBER**

The style number appears on the front panel, drawout cradle, and inside the case assembly. This style number is an alphanumeric combination of characters identifying the features included in a particular unit. The sample style number below illustrates the manner in which the various features are designated. The Style Number Identification Chart (page 12) defines each of the options and characteristics available for this device.

**SAMPLE STYLE NUMBER A1EA1PA0N2F**

The style number above describes a BE1-32R Directional Power Relay having the following features.

- Sensing Input Type (A) Single-phase current and L-N voltage sensing
- Sensing Input Range (1) 120 Vac, 0.5-20W
- Output (E) One Output relay with normally open contacts
- Timing (A1) Instantaneous timing
- Power Supply (P) 125 Vdc/120 Vac input power supply
- Target (A) One internally operated target
- Option 1 (0) None
- Option 2 (N) None
- Option 3 (2) One auxiliary output relay with normally closed contacts
- Option 4 (F) Semi-flush mounting

**HOW TO ORDER:**

Designate the model number followed by the complete Style Number.

Complete the Style Number by selecting one feature from each column of the Style Number Identification Chart and entering its designation letter or number into the appropriate square. (Two squares are used to indicate time delay characteristics.) All squares must be completed.

**STANDARD ACCESSORIES:**

The following accessories are available for the BE1-32R or BE1-32 O/U Directional Power Relays.

**Test Plug**

To allow testing of the relay without removing system wiring, order two test plugs, Basler Electric part number 10095.

**Extender Board**

The extender board permits troubleshooting of the printed circuit boards outside of the relay cradle. Order Basler Electric part number 9165500100.
### STYLE NUMBER IDENTIFICATION CHART

#### BE1-32R, BE1-32O/U

##### SENSING INPUT TYPE

- **A)** Single-phase L-N Voltage
- **B)** Single-phase L-L Voltage 30° phase shift (60 Hz)
- **C)** Single-phase Current, Three-phase (Open Delta) Voltage, Scott T
- **D)** Three-phase Current, Three-phase (Wye) Voltage, Two Element
- **E)** Two-phase Current, Three-phase (Open Delta) Voltage, Two Element
- **V)** Single-phase L-L Voltage 30° phase shift (50 Hz)

##### OUTPUT

- **E)** One relay - NO BE1-32R only
- **F)** Two relays - NO BE1-32O/U
- **G)** One relay - NC BE1-32R
- **H)** Two relays - NC BE1-32O/U
- **N)** Two relays BE1-32O/U over - NO under - NC
- **P)** Two relays BE1-32O/U over - NC under - NO

##### POWER SUPPLY

- **O)** 48 Vdc
- **P)** 125 Vdc/120Vac
- **R)** 24 Vdc
- **T)** 250 Vdc/240 Vac

##### OPTION 1

- **F)** Semi-Flush Mounting
- **P)** Projection Mounting

##### OPTION 2

- **N)** None
- **A)** One internally operated target-BE1-32R
- **B)** One current operated target-BE1-32R
- **C)** Two internally operated targets, BE1-32O/U
- **D)** Two current operated targets, BE1-32O/U
- **E)** Two targets, BE1-32O/U over-internally operated under-current operated
- **F)** Two targets, BE1-32O/U over-current operated under-internally operated

##### OPTION 3

- **N)** None
- **1)** One auxiliary relay - NO
- **2)** One auxiliary relay - NC
- **3)** Two auxiliary relays - NO BE1-32O/U
- **4)** Two auxiliary relays - NC BE1-32O/U
- **5)** One auxiliary relay - SPDT
- **7)** Two auxiliary relays, BE1-32O/U over - NO Under - NC
- **8)** Two auxiliary relays, BE1-32O/U over - NC under - NO

##### OPTION 4

- **N)** None
- **F)** One relay - NO
- **P)** Two relays - NO
- **N)** None
- **S)** Power supply status output

#### TIMING

- **A1)** Instantaneous:
  - one setpoint-BE1-32R
  - two setpoints-BE1-32O/U
- **D1)** Inverse time:
  - one adjustment-BE1-32R
- **D3)** Inverse - over (0.1-99 sec)
- **E1)** Definite time (0.1-99 sec):
  - one adjustment-BE1-32R
  - two adjustments-BE1-32O/U
- **E2)** BE1-32O/U Under-definite time (0.1-99 sec)

#### TARGET

- **N)** None
- **A)** One internally operated target-BE1-32R
- **B)** One current operated target-BE1-32R
- **D)** Two current operated targets, BE1-32O/U
- **E)** Two targets, BE1-32O/U over-current operated under-current operated

#### SENSING INPUT RANGE

1. **120 Vac, 0.5-20W (A,B,V) or 1.5-60W (C,D,E)
2. **120 Vac, 5-200W (A,B,V) or 15-600W (C,D,E)
3. **120 Vac, 25-1000W (A,B,V) or 75-3000W (C,D,E)
4. **208 Vac, 1-40W (A,B,V) or 3-120W (C,D,E)
5. **208 Vac, 10-400W (A,B,V) or 30-1200W (C,D,E)
6. **208 Vac, 50-2000W (A,B,V) or 150-6000W (C,D,E)
7. **240 Vac, 1-40W (A,B,V) or 3-120W (C,D,E)
8. **240 Vac, 10-400W (A,B,V) or 30-1200W (C,D,E)
9. **240 Vac, 50-2000W (A,B,V) or 150-6000W (C,D,E)

#### NOTES:

1. For use with the Sensing Input Type indicated in parentheses.
2. Current operated targets may be selected only when N.O. type output contacts are selected. Internally operated targets should be selected if the breaker control (trip) circuit is AC powered or the relay has N.C. type output contacts.
3. Option 3-4,5,7 or 8 may be selected only when Option 2 is N.
4. If model number is BE1-32O/U and Option 3 is 1,2, or 5 the associated auxiliary relay output applies to the overpower function only.
5. Sensing Input Types D and E require M1 case.